WACHENDORFF

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Set - Guided belt measuring unit Silent Move light WDGMEMZ For heights up to 120 metres (393.70 ft)



- Quiet and non-slip digital shaft copying for universal mounting on a lift cabin
- Use up to speeds of 4 m/s (800 ft/min).
- Particularly quiet and smooth-running, thanks to special belts and low-noise suspension.
- User-friendly, reliable alternative to switches and sensors.
- Accuracy in the shaft:
 - Incremental encoder WDGI58B
 0.072 mm/pulse (0.002834 inch/pulse) 5,000 pulses
- Absolute encoder WDGA58B multiturn, with CANopen interface:4,096 steps/turn and 262,144 (18 bit multiturn) turns, CANopen LIFT interface:4,096 steps/turn and 262,144 (18 bit multiturn) turns or SSI interface: 4,096 (12 bit) steps/turn and 8,192 (13 bit multiturn) turns
- Fast and flexible installation with complete set of mechanical parts.

www.wachendorff-automation.com/silent-move

Put together your own measuring unit for shaft copying, by selecting an encoder and specifying the length of the special belt.



Incremental encoder WDGI58B

Incremental encoders WDGI:

Calculation of resolution in the shaft: Effective circumfrerence of pulley: 360 mm (14.1732283465 inch)

| Res. ir | n mm | ı (in | ch) = | 360 mm (14.1732283465 inch) Pulse number of encoder (PPR) |
|---------|------|-------|-------|--|
| | | | | Pulse number of encoder (PPR) |

| Res. in pulses/mm (inch) | _ | Pulse number of encoder (PPR) |
|--------------------------|---|-------------------------------|
| | _ | 360 mm (14.1732283465 inch) |

Calculation of the limit frequency:

fg (Hz) = $\frac{\text{Pulse number of encoder} (\text{PPR}) \text{ x max. speed (m/sec) (ft/sec)}}{0.36 \text{ m} (1.1811 \text{ ft})}$

Calculation of the traverse path:

s (m) (ft) = $\frac{\text{Pulses (l)}}{\text{Pulse number of encoder (PPR)}} \times 0,36 \text{ m (1.1811 ft)}$



Absolute encoder WDGA58B

Absolute encoders WDGA:

Repeat precision with WDGA: +/- 0.2 mm (0.007874 inch)



Special belt for exceptionally quiet, non-slip measuring.

Ordering information - Guided belt landing system WDGMEMZ:

| Description: | Order No.: |
|---|--|
| Unit (without encoder): Belt pulley, 2 tensioning rollers, encoder attachment, attachment of the belt in the shaft, tensioning device and fixing for the belt. Please order the special belt separately. (see below: Silent Move special belt, calculation of length) | WDGMEMZ |
| Incremental variants** Unit with incremental encoder 58B10600ABNH24K3: For an accuracy of measurement of 0.6 mm (0.02362 inch) or 1.6 pulses/mm (42.3 pulses/inch) with a limit frequency of 6.6 kHz and a cab speed of 4 m/s (787.4 ft/min). Encoder type 58B10600ABNG24K3: Shaft: Ø 10 mm, pulse number: 600 PPR, channels: AB and zero pulse, G24: 10 up to 30 VDC, channels push-pull, K3: lead outlet 2 m cable, radial | WDGMEMZ58B10600ABNH24K3 |
| Unit with incremental encoder 58B101000ABNH24K3: For an accuracy of measurement of 0.36 mm (0.01417 inch) or 2.7 pulses per mm (70.5 pulses per inch) with a limit frequency of 11.1 kHz and a cab speed of 4 m/s (787.4 ft/min). Encoder type 58B101000ABNG24K3: Shaft: Ø 10 mm, pulse number: 1,000 PPR, channels: AB and zero pulse, G24: 10 VDC up to 30 VDC, channels push-pull, K3: lead outlet 2 m cable, radial | WDGMEMZ58B101000ABNH24K3 |
| Unit with inkremental encoder 58B102500ABNH24K3: For an accuracy of measurement of 0.144 mm (0.005669 inch) or 6,94 pulses/mm (176.38 pulses/inch) with a limit frequency of 27.7 kHz and a cab speed of 4 m/s (787.4 ft/min). Encoder type 58B102500ABNH24K3: Shaft: Ø 10 mm, pulse number: 2,500 PPR, channels: AB and zero pulse, H24: 10 VDC up to 30 VDC, channels push-pull, K3: lead outlet 2 m cable, radial | WDGMEMZ58B102500ABNH24K3 |
| Find your incremental encoder: With the aid of the calculation forms for limit frequency and resolution in the shaft and the data sheet WDGI58B. All variants defined except optional shaft sealed to IP67. | WDGMEMZ58B10XXXXYYYZZZSC8 |
| Absolute variants WDGA58B CANopen. CANopen LIFT or WDGA58B SSI** Unit with absolute multitum encoder with CANopen CiA 406 interface: For an accuracy of measurement of 0.088 mm (0.0035 inch) or 11.38 steps/mm (289 steps/inch). Binary code: 4,096 (12 bit) steps/revolution and max. 262,144 (18 bit) revolutions. 10 VDC up to 30 VDC, clamping flange, 5 pin. connector, radial, 10 m bus line with connector and female connector, T-junction, termination resistor. | WDGMEMZ58B101218COAB00CC5 |
| Unit with absolute multitum encoder with CANopen LIFT CiA 417 interface: For an accuracy of measurement of 0.088 mm (0.0035 inch) or 11.38 steps/mm (289 steps/inch) configurable. Binary Code: 4,096 (12 bit) steps/revolution and max. 262,144 (18 bit) revolutions configurable. Power supply 10 VDC up to 30 VDC, 5 pin. connector, radial, 10 m bus line with connector and female connector, T-junction, termination resistor. | WDGMEMZ58B101218CLAB00CC5 |
| Unit with absolute multitum encoder with SSI interface*: For an accuracy of measurement of 0.088 mm (0.0035 inch) or 11.38 steps/mm (289 steps/inch). * Gray Code (G)/Binary Code (B): 4,096 (12 bit) steps/revolution and 8,192 (13 bit) revolutions. 10 VDC up to 30 VDC, clamping flange, lead outlet 2 m cable, radial | WDGMEMZ58B101218SIAX01L3 X = G or B |
| Comprehensive technical information on WDGA 58B CANopen / WDGA 58B CANopen LIFT / WDGA 58B SSI - www.wachendorff-automation.com/wdga58bcan /wdga58bcanlift /wdga58bssi | |
| For encoders with connector always excl. connection cable (exception CANopen & CANopen LIFT systems) Suitable connection cable: KI-9-67-xx-S (incremental), KI-8-67-xx-SSI (SSI) or KI-8-67-xx-EIA (RS485); xx= cable length | |
| Silent Move light special tooth belt: Calculation of the length: Transport height + 5 m (extend accordingly for transition points) 20 m 35 m 50 m 60 m 80 m 430 m-drum Special tooth belt (XXX = figures in metres) | WDGZR020 WDGZR035 WDGZR050 WDGZR060 WDGZR080 WDGZR430 WDGZRXXX |

Customs tariff number: 90318020 Country of origin: 90318020